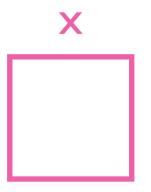
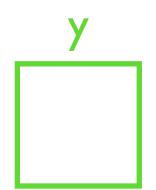


- Where is x defined?
 - x = 5 ptr = &x *ptr = 9y = x



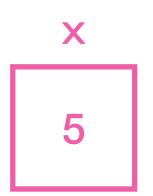


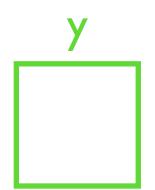




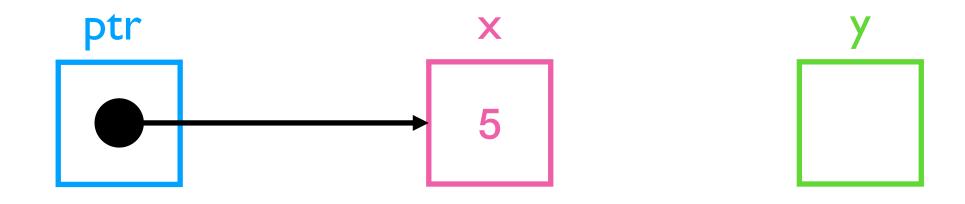
- Where is x defined?
 - x = 5 ptr = &x *ptr = 9y = x



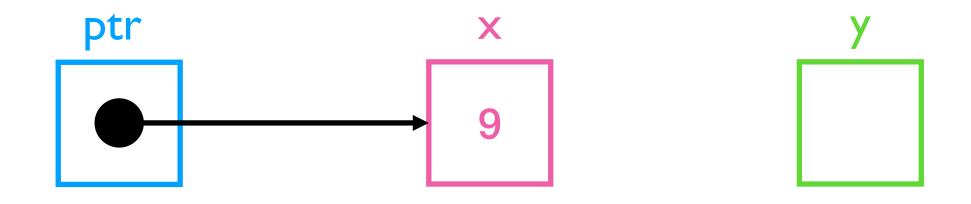




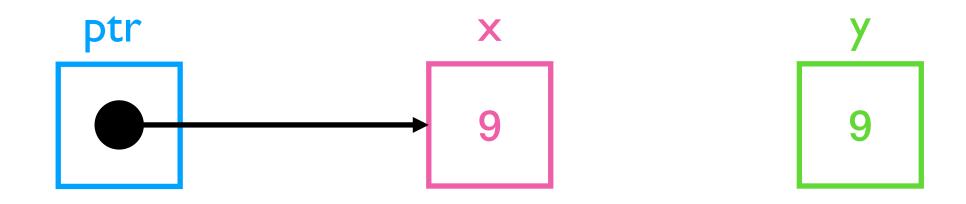
- Where is x defined?
 - x = 5 ptr = &x *ptr = 9y = x



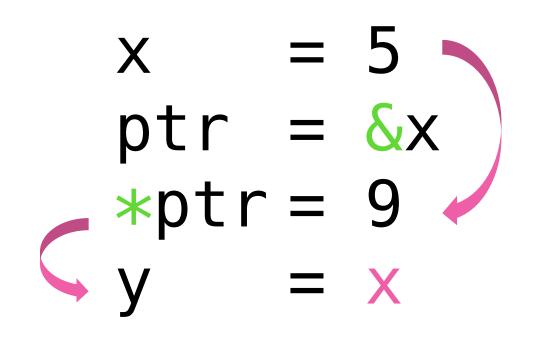
- Where is x defined?
 - x = 5 ptr = &x *ptr = 9y = x

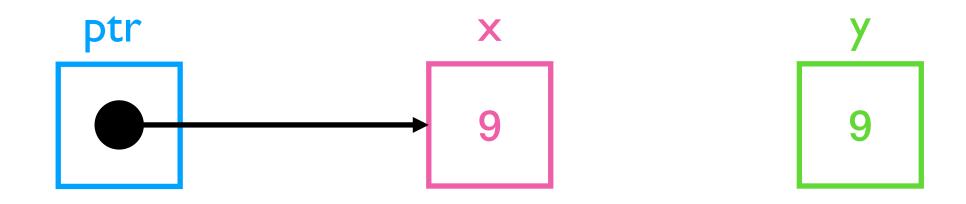


- Where is x defined?
 - x = 5 ptr = &x *ptr = 9y = x

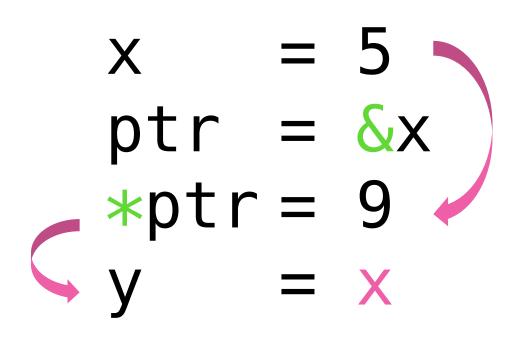


• Where is x defined?

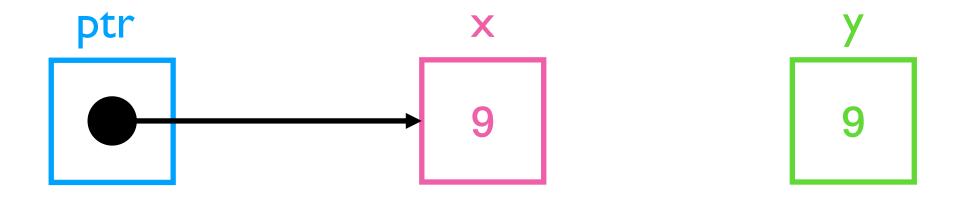




• Where is x defined?



- Problem: just looking at variable names does not give you the right answer
- Must know (or estimate) this points to information for correct analysis



• Both *ptr and x talk about the same memory location (ptr points to x)

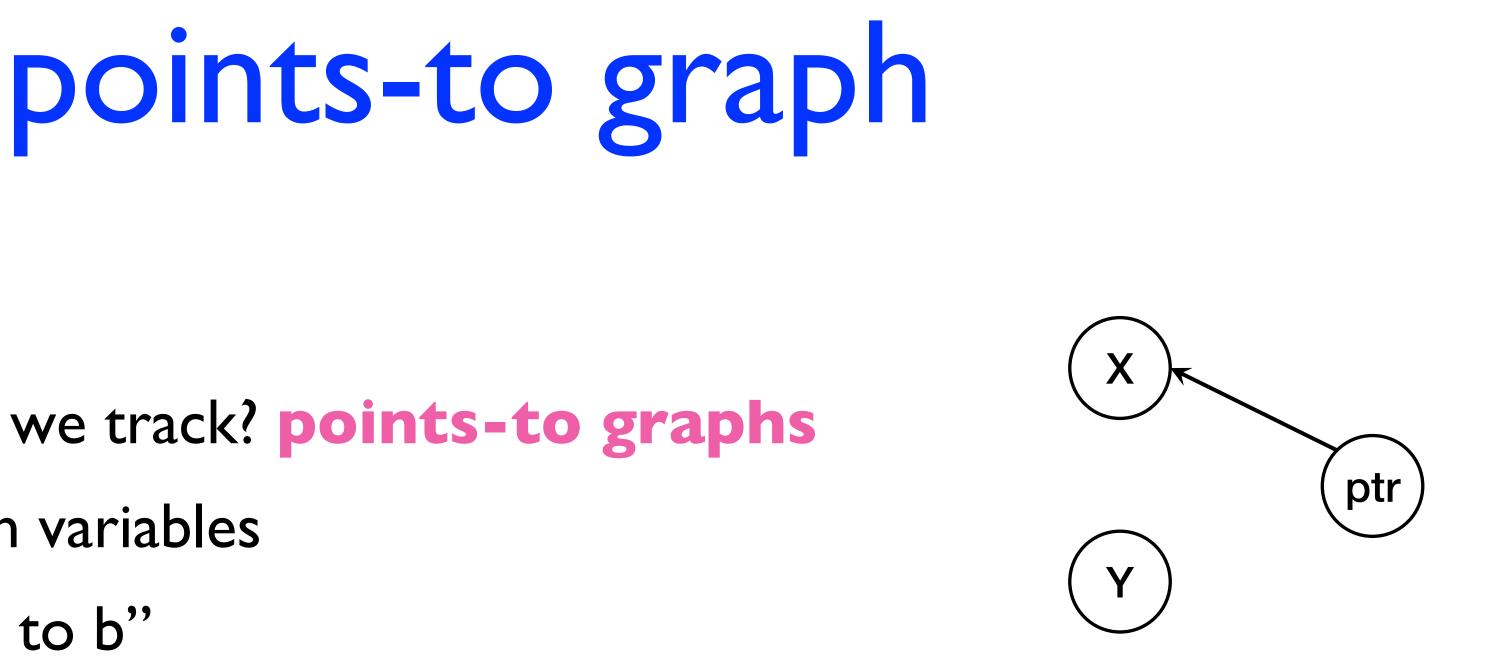
program model

- For now, types are simple: base type is int, or pointer (*) to another type
- No function calls, no pointer arithmetic
- Statements using pointer variables

Address of: x = &yCopy: x = yLoad: x = *yStore: *x = y

Arbitrary computations involving ints

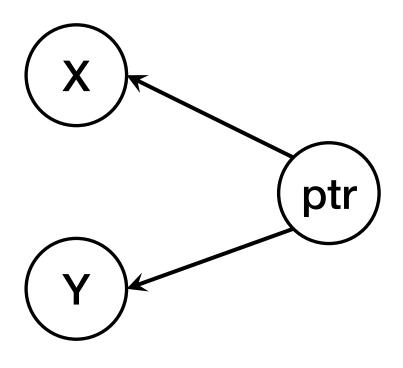
- What information do we track? points-to graphs
 - Nodes are program variables
 - Edges say "a points to b"
- Points-to graph can be different at different points



• Can use a special node for NULL, a special node for "somewhere in the heap"

- Out-degree of a node can be more than one
 - Node with multiple outgoing edges says "a may point to b or c"
 - Represents uncertainty in the analysis
 - e.g., if more than one way to reach a program point

points-to graph



t to?

making a lattice

- To create a lattice, we need a \perp , a \top and a \sqsubseteq
 - \perp is "graph with no edges"
 - \top is "graph with all nodes pointing to all other nodes"
- $G_1 \sqsubseteq G_2$ if and only if G_2 has all of the edges G_1 has, and maybe some more
- What about join (\sqcup) and meet (\sqcap) ?
 - $G_1 \sqcup G_2$ = graph with the *union* of the edges in both graphs
 - $G_1 \sqcap G_2$ = graph with the *intersection* of the edges in both graphs



- Two different kinds of pointer analyses
 - flow-sensitive: standard dataflow analysis --- what is the points-to graph at each point in the program?
 - flow-insensitive: simplification --- what if we construct a single points-to graph that is valid at all points in the program? (Overapproximates flow-sensitive result)

gameplan

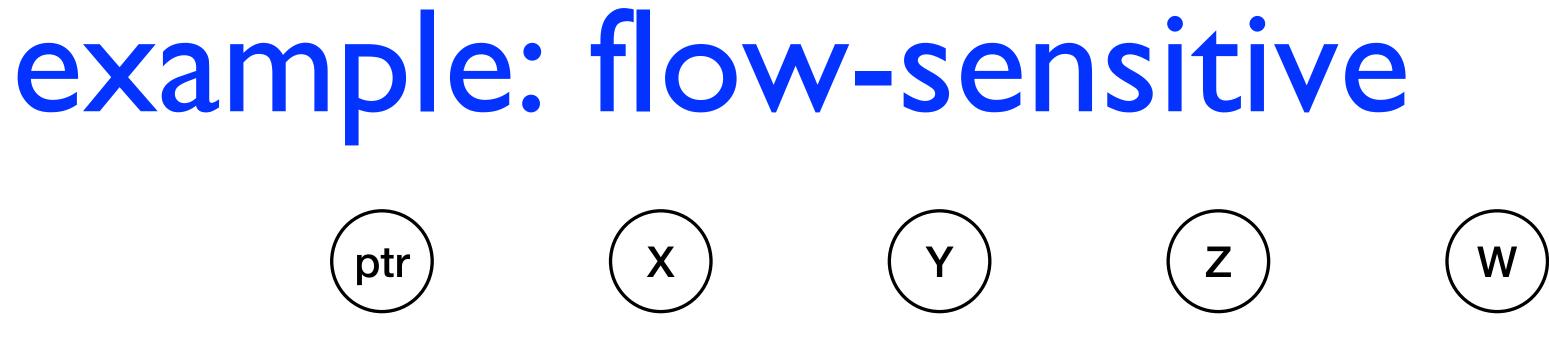


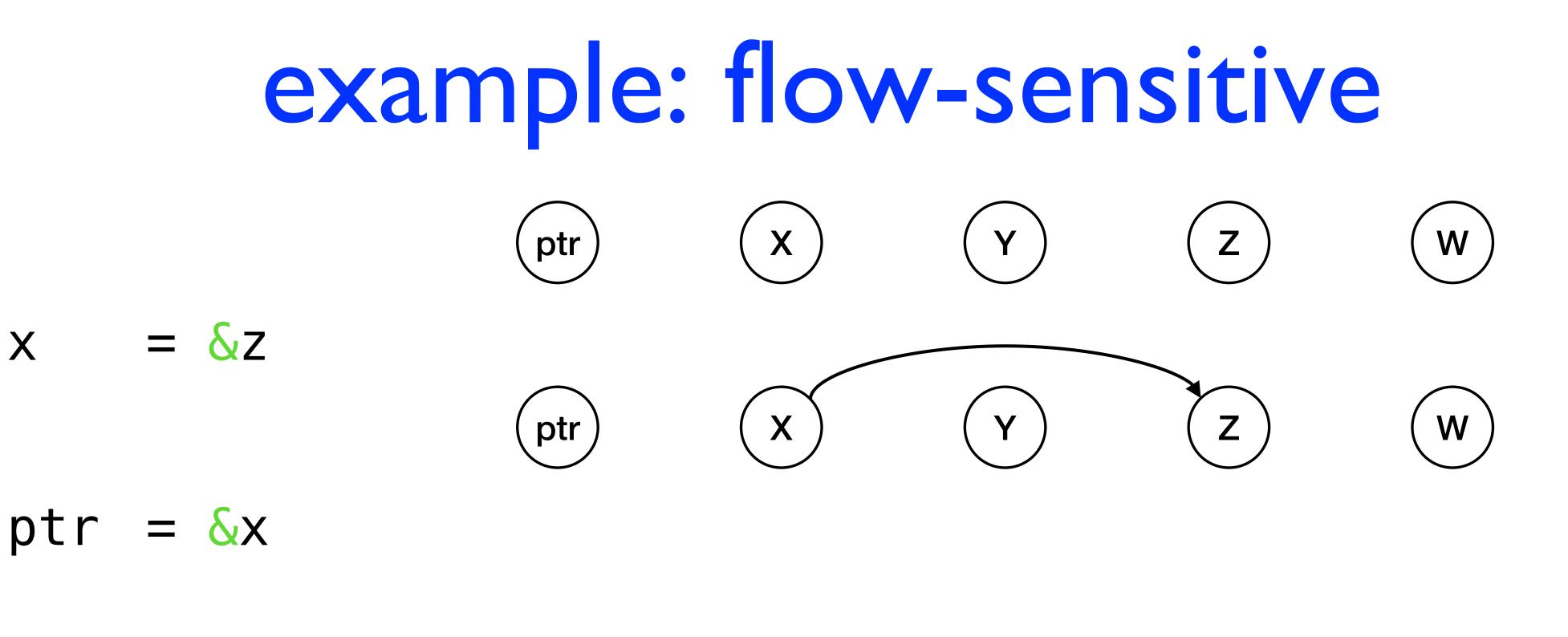
$X = \delta Z$

$ptr = \delta x$

 $y = \delta W$

 $ptr = \delta y$

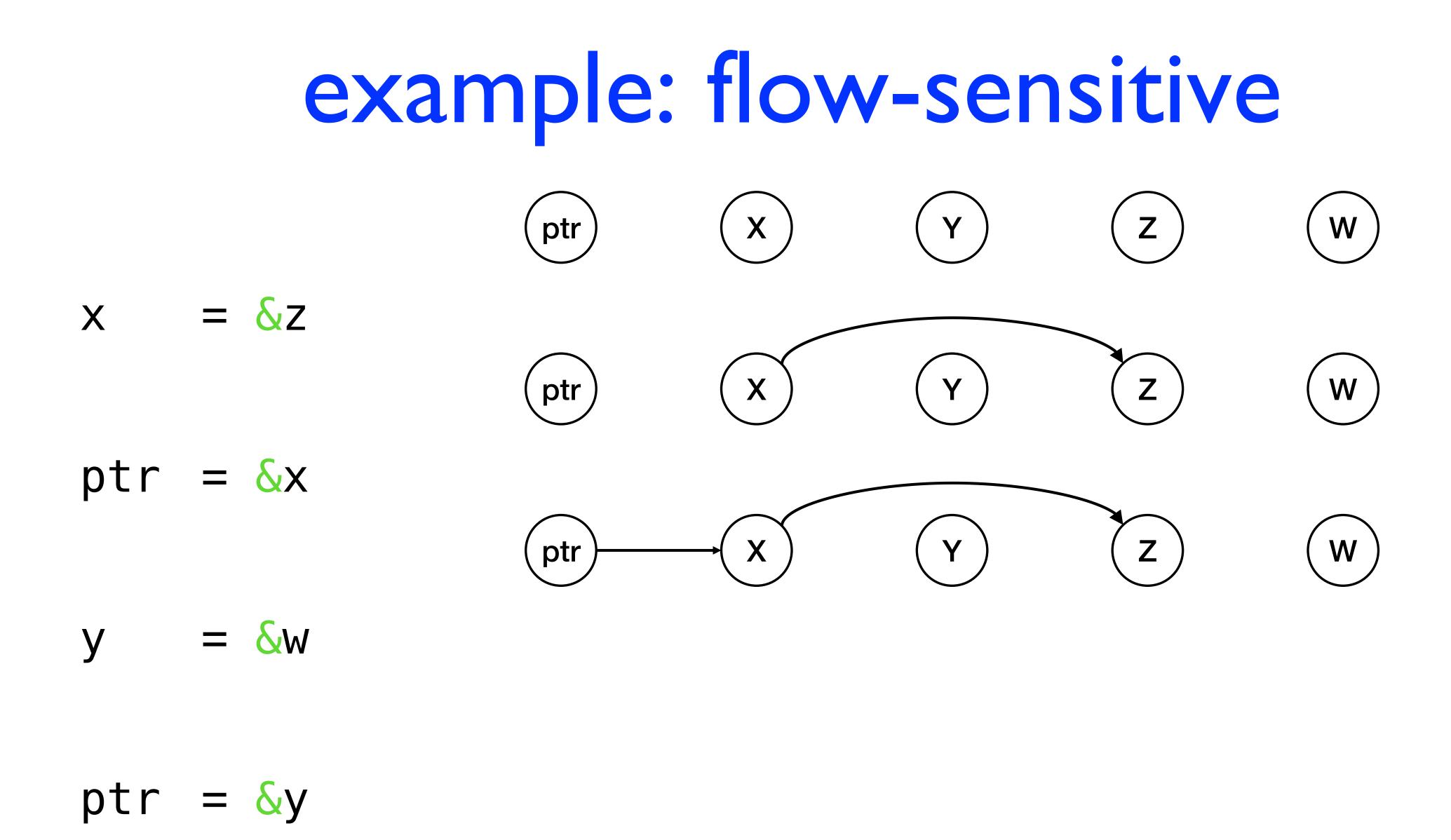


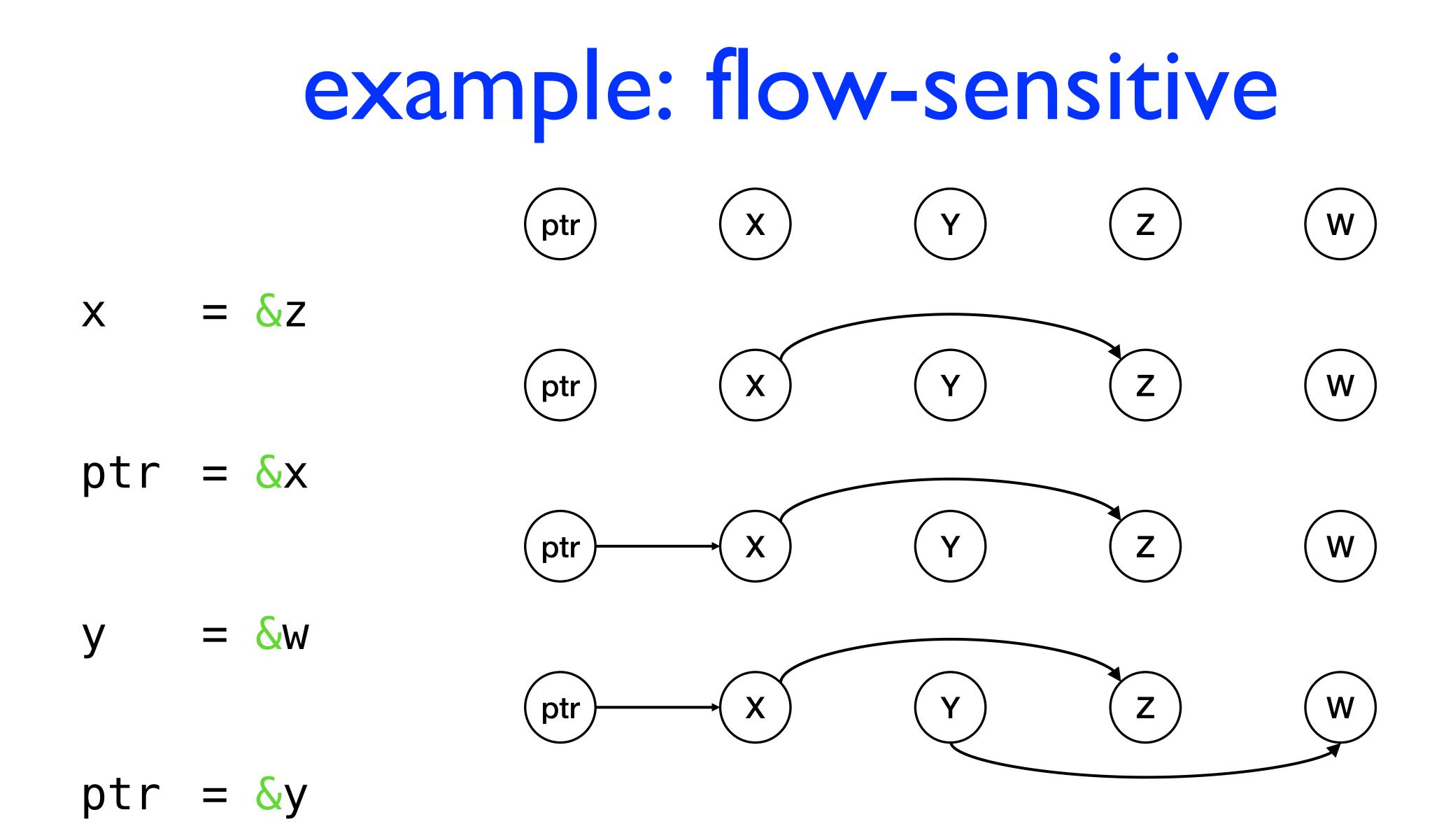


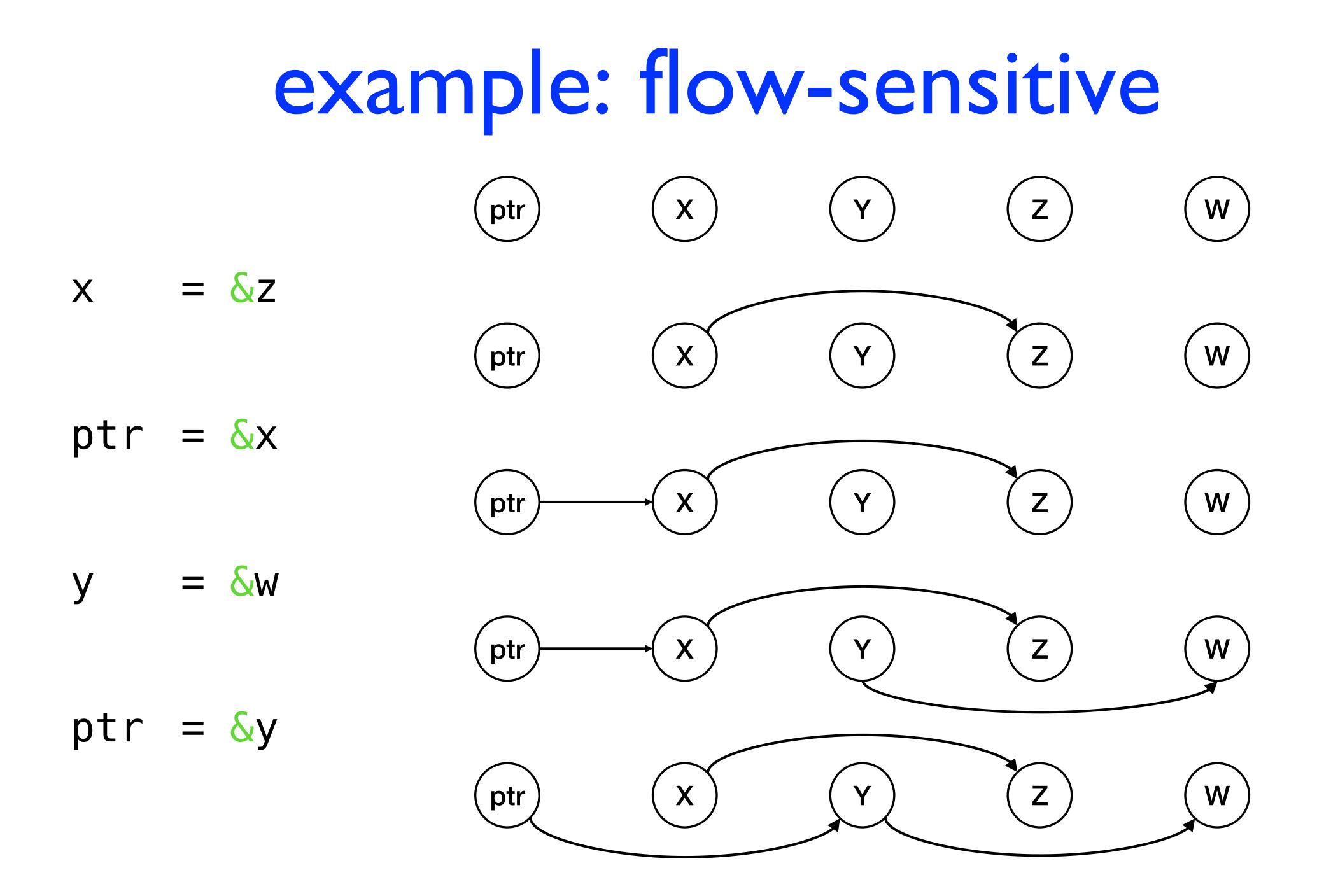
 $W \delta = \delta W$ У

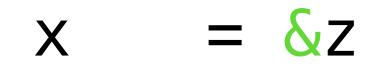
Χ

ptr = & V

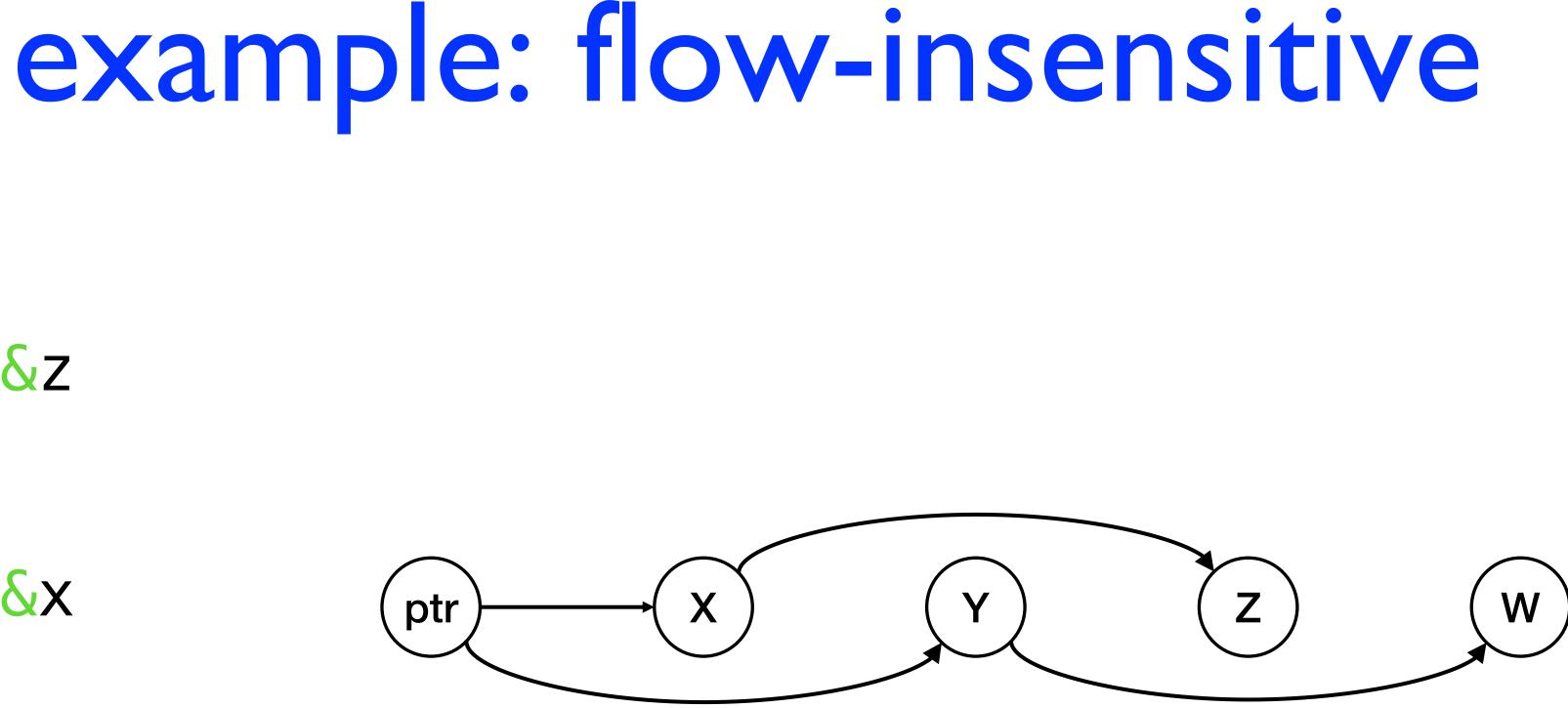








ptr = &x



 $= \delta W$ У

ptr points to x or y because we only have one points-to graph

ptr = & V

next: flow-sensitive pointer-analysis